

# Exponential random graphs

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MoN4 QMUL 2005 Jul 22 1215

corrected version 2005 July 25 16:18

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# Shi Zhou and Raúl Mondragón

## ★ *Accurately modeling the internet topology*

Phys. Rev. E **70** 066108 (2004) ■

## ★ Network parameters: ■

- ▷ *number of nodes, ■ number of links, ■ average degree, ■ exponent of power law, ■ rich-club connectivity, ■ maximum degree, ■ degree distribution, ■ characteristic path length, ■ average triangle coefficient, ■ maximum triangle coefficient, ■ average quadrangle coefficient, ■ maximum quadrangle coefficient, ■ average  $k_{mn}$ , ■ average betweenness, ■ maximum betweenness. . . ■*
- ▷ *girth, spectrum, . . . ■*

# Motivation

- ★ we use many random graph models in network applications. . . ■
- ★ but rarely specify the statistical ensemble precisely ■
- ★ so even the averages we compute are suspect ■
- ★ and even the famous Barabási-Albert scale-free model has known problems ■

we need a unified, rigorous framework ■

## ★ related ideas in earlier literature:

- ▷ *Markov random fields* ■
- ▷  *$p^*$  models of social networks* ■
- ▷ *Ising-type models in physics* ■
- ▷ *agricultural field trials* ■
- ▷ *image processing* ■
- ▷ . . .

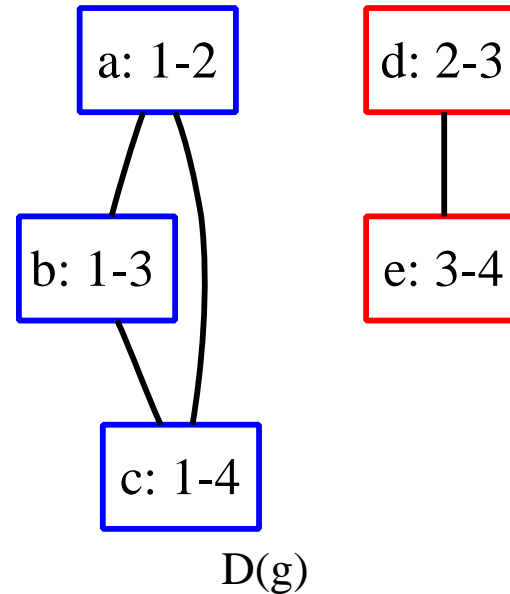
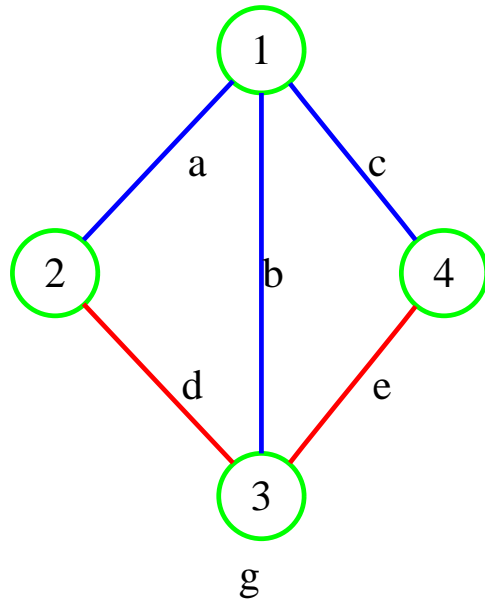
# Dependency graphs (Frank, Strauss, Besag, . . . )

- ★ consider a random vector  $X = (X_1, X_2, \dots, X_m)$  ■
- ★  $P(x) = \exp(Q(x)) / \sum \exp Q(x) \Leftrightarrow Q(x) = \log P(x) + \text{const}$ 
  - ▷ *only restriction*  $P(x) > 0 \quad \forall x$  ■
- ★ let  $D$  be the *dependency graph* of  $X$ ; i.e.  $i \sim j \Leftrightarrow x_i$  not independent of  $x_j$  ■
  - ▷ e.g. all  $x_i$  independent: empty graph ■
  - ▷ e.g. Markov chain: line graph ■
  - ▷ e.g. multivariate Gaussian: complete graph (generically) ■
- ★ inclusion-exclusion principle  $Q(x) = \sum_{s \subseteq \{1, 2, \dots, m\}} \lambda_s(x_s)$  ■
  - ▷  $x_s \equiv$  components of  $x$  corresponding to elements of  $s$  ■
  - ▷  $\Pr[\cap_i A_i] = \sum_i \Pr[A_i] - \sum_{i < j} \Pr[A_i \cup A_j] + \dots$  ■
- ★ Hammersley-Clifford theorem:  $\lambda_s \equiv 0$  unless  $s$  is a clique of  $D$ 
  - ▷ a *clique* is a complete subgraph

# Markov graphs

- ★ to apply to a graph  $g$  with edge dependencies, let  $X$  be the edge indicator functions ■
- ★ this defines the dependency graph  $D(g)$  of  $g$ :  $D(g)$  contains an edge  $(i, j)$  if  $X_i$  and  $X_j$  ( $i \neq j$ ) are dependent ■
- ★ definition:  $g$  is *Markov* if  $D(g)$  contains no edge between edges which are disjoint in  $E(g)$  ■
- ★ in other words, edges can only 'interact' if they share a common end-point

# Markov graph example ( $n = 4, m = 5$ )



★ cliques:  $\{\{a\}, \{b\}, \{c\}, \{d\}, \{e\}, \{a, b\}, \{b, c\}, \{a, c\}, \{d, e\}, \{a, b, c\}\}$  ■

★ thus

$$\begin{aligned}
 Q(x) &= \lambda_a(x_a) + \lambda_b(x_b) + \lambda_c(x_c) + \lambda_d(x_d) + \lambda_e(x_e) \\
 &+ \lambda_{ab}(x_a, x_b) + \lambda_{bc}(x_b, x_c) + \lambda_{ac}(x_a, x_c) + \lambda_{de}(x_d, x_e) \\
 &+ \lambda_{abc}(x_a, x_b, x_c)
 \end{aligned}$$

# Homogeneous Markov graphs 1

- ★ if we require all isomorphic graphs to have the same probability, then a further simplification results: ■
- ★ let  $t(g)$  be the number of triangles in  $g$  ■
- ★ let  $s_k(g)$  be the number of  $k$ -stars in  $g$  ■
- ★ then  $P(g)$  can *only* depend on  $t(g)$  and  $s_k(g)$ , in the form

$$P_{\beta}(g) = \frac{1}{Z(\beta)} \exp \left[ \beta_0 t(g) + \sum_{k=1}^{n-1} \beta_k s_k(g) \right]$$

where  $\beta_i$  are fixed parameters ■

- ★ here  $Z(\beta) = \sum_g \exp \left[ \beta_0 t(g) + \sum_{k=1}^{n-1} \beta_k s_k(g) \right]$

## Homogeneous Markov graphs 2

- ★ alternatively, we may use  $d_j$ , the number of nodes of degree  $j$  ( $s_k(g) \equiv \sum_{j \geq k} \binom{j}{k} d_j(g)$ ) ■
- ★ and let  $\theta_k(g) \equiv \sum_{k \leq j} \binom{j}{k} \beta_k$ ; then

$$P_\theta(g) = \frac{1}{Z(\theta)} \exp \left[ \theta_0 t(g) + \sum_{j=1}^{n-1} \theta_j d_j(g) \right] \quad \blacksquare$$

- ★ in other words, the Hamiltonian *can only be* a linear function of the number of triangles and  $k$ -stars ■
- ★ note: if  $A$  is the adjacency matrix of  $g$ , then  $m(g) = d_1(g) = \text{tr}(A^2) / 2$  is the number of edges and  $t(g) = \text{tr}(A^3) / 6$



# Exponential random graphs

- ★ fix a number of nodes  $n$  ■
- ★ consider the set  $G(n)$  of all graphs on  $n$  nodes ■
- ★ we will assign to each  $g \in G(n)$  a probability  $P(g)$  ■
- ★ let  $x = \{x_1, x_2, \dots\}$  be a set of functions on  $G(n)$  representing properties we are interested in, for example
  - ▷  $x_1(g)$ =number of edges
  - ▷  $x_2(g)$ =number of nodes of degree 3
  - ▷  $x_3(g)$ =number of triangles ■
- ★ we then assign the probabilities  $P$  by

$$P_{\theta}(g) = \frac{1}{Z(\theta)} \exp(\theta_1 x_1 + \theta_2 x_2 + \dots)$$

where  $Z(\theta) = \sum_{g \in G(n)} \exp(\theta_1 x_1 + \theta_2 x_2 + \dots)$

# Statistical mechanics

- ★ Hamiltonian:  $H(\theta, g) = \sum_i \theta_i x_i(g)$  ■
- ★ probability of  $g$ :  $P_\theta(g) = \exp(H(\theta, g)) / Z(\theta)$  ■
- ★ partition function:  $Z(\theta) = \sum_g \exp(H(\theta, g))$  ■
- ★ entropy  $S(\theta) = - \sum_g P_\theta(g) \log(P_\theta(g))$  ■
- ★  $S$  is maximized by our choice of  $P$  ■
- ★ free energy:  $F(\theta) = \log(Z(\theta))$  ■
- ★  $\mathbf{E}[x_i] = \frac{dF(\theta)}{d\theta_i}$

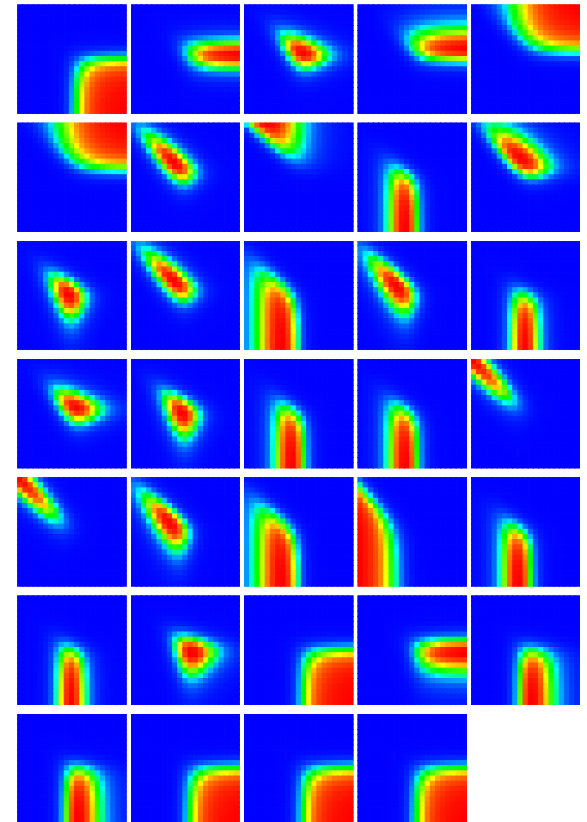
## Exactly soluble example - Bernoulli model $G\{n, p\}$

- ★  $g \in G\{n, p\}$  has  $n$  nodes and each possible edge appears independently with fixed probability  $p$  ■
- ★ let  $x(g) =$  number of edges in graph  $g$  ■
- ★  $H(\theta, g) = \theta m(g)$  ■
- ★  $Z(\theta) = (1 + \exp(-\theta))^{\binom{n}{2}}$  ■
- ★  $p = 1/(1 + \exp(\theta))$
- ★  $F(\theta) = \binom{n}{2} \log(1 + \exp(-\theta))$  ■
- ★ which gives  $P_p(g) = \binom{n}{m(g)} p^{m(g)} (1-p)^{\binom{n}{2} - m(g)}$  as expected ■
- ★  $\mathbf{E}[x] = m = \binom{n}{2} p$

# Example - exact likelihood for all 5-node graphs

Likelihood of parameters, given a graph:  $L(\theta|g) \propto P_\theta(g)$ . (Loglikelihood:  $l(\theta|g) \equiv \log P_\theta(g) + \text{const.}$ )

Each figure shows the likelihood for one of the 34 graphs, the parameters corresponding to the number of nodes of degrees one and two. i.e.  $H_\theta(g) = \theta_1 d_1(g) + \theta_2 d_2(g)$



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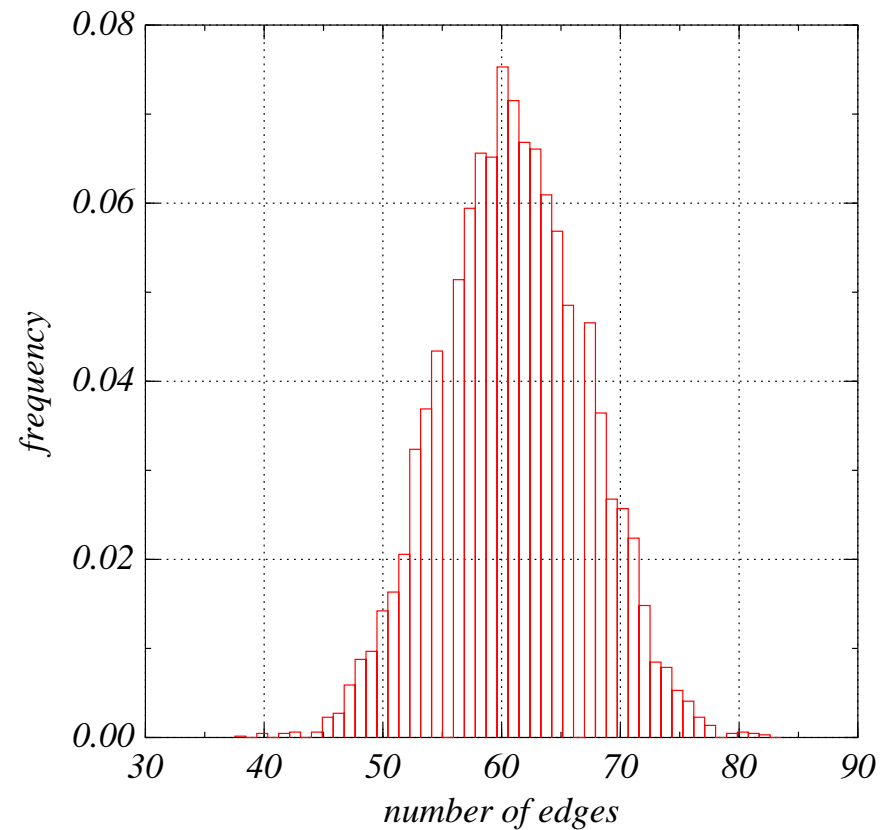
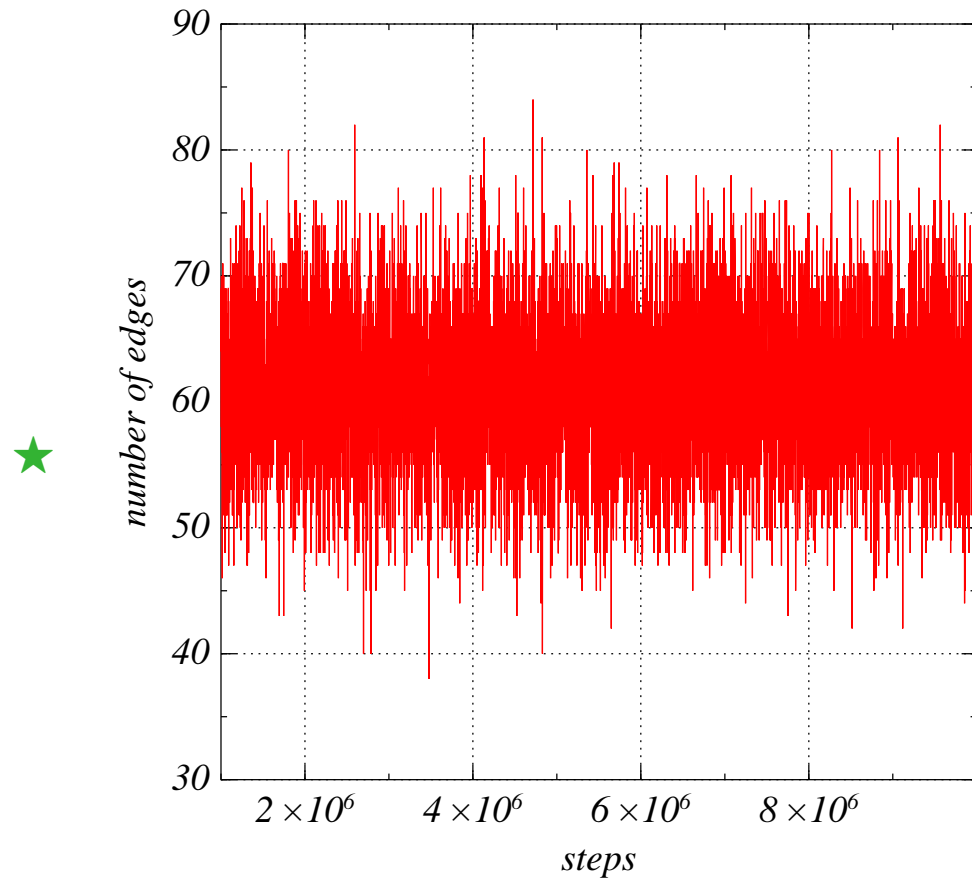
# Metropolis simulation

- ★ works by defining a random walk in  $G$  which has equilibrium distribution equal to our desired  $P$  ■
- ★ typically we choose a pair of nodes, and then flip its state depending on whether the flip is energetically favourable ■
  - (1) choose a *proposal dyad*  $i, j \in N(g)$  uniformly at random ■
  - (2) compute the energy change  $\delta H$  that would occur if the dyad  $(i, j)$  were flipped ■
  - (3) if  $\delta H < 0$  or  $u < \exp(-\delta H)$ ,  $u \sim U(0, 1)$ , then accept the proposal; i.e. flip the edge ■
  - (4) go to (1) ■
- ★ estimate loglikelihood by (where  $x$  is the vector of graph statistics,  $\theta_{\text{ref}}$  a reference value of graph parameters (hopefully close to the true ones) and  $x_{\text{data}}$  the statistics from the data):

$$l(\theta) - l(\theta_{\text{ref}}) \approx -\log \langle \exp[(l(\theta) - l(\theta_{\text{ref}})) \cdot (x(t) - x_{\text{data}})] \rangle$$

# Metropolis simulation example

- ★ 18 nodes; graph shows fluctuations in  $m(g)$



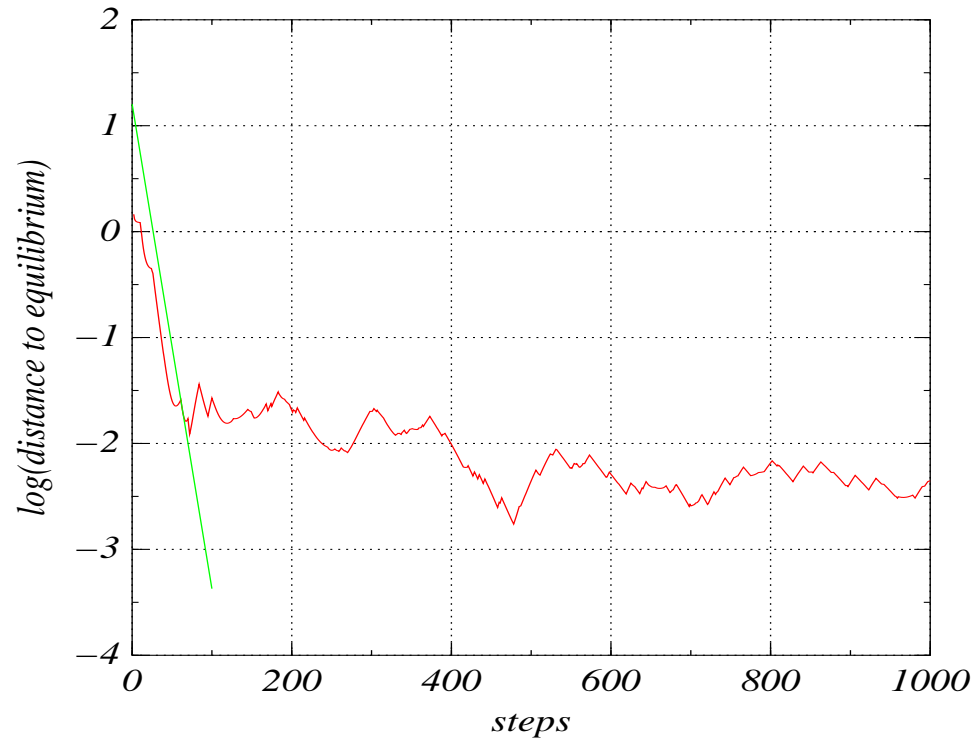
# Metropolised independence sampling (MIS) 1

- ★ consider the target distribution  $\pi_\theta(j) = \exp(j \log \theta) / Z(\theta)$ ,  $Z(\theta) \equiv (1 - \theta^n) / (1 - \theta)$  on the set  $\{0, 1, 2, \dots, n-1\}$  ■
- ★ an MIS scheme is ■
  - (0) start at  $x = n-1$  ■
  - (1) choose a *proposal*  $y \in X$  uniformly at random ■
  - (2) if  $y < x$  or  $u < \theta^{y-x}$ ,  $u \sim U(0, 1)$ , then accept the proposal;  
i.e. set  $x = y$  ■
  - (3) go to (1) ■
- ★ note that this scheme ignores the current position  $x$  and assumes no knowledge of  $\pi$ . In general, we can do better

## Metropolised independence sampling 2

- ★ for this example, it can be proven [Diaconis & Saloff-Coste 1998] that

$$4 \|M^k - \pi\| \leq \frac{1}{(1-\theta)(\theta^{n-1})} \left(1 - \frac{1}{n}\right)^{2k}$$





## What next?

- ★ directed graphs ■
- ★ perturbation theory (around Bernoulli model?) ■
- ★ more rapidly converging sampling schemes ■
- ★ parameter estimation for real examples by maximum likelihood (e.g. internet AS graph) ■
- ★ . . . ?

## Some references (amongst many)

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